

## ADAPTING PLC/SCADA SYSTEMS TO MITIGATE INDUSTRIAL IOT CYBERSECURITY RISKS IN GLOBAL MANUFACTURING

Jabed Hasan Tarek<sup>1</sup>; Zayadul Hasan<sup>2</sup>;

- [1]. Phillip M. Drayer Department of Electrical Engineering, Lamar University, Beaumont, Texas, USA; Email: [jabedhasan932@gmail.com](mailto:jabedhasan932@gmail.com)
- [2]. Department of Electrical and Electronics Engineering, American International University Bangladesh, Bangladesh; Email: [zayadulhasan@gmail.com](mailto:zayadulhasan@gmail.com)

### ABSTRACT

The convergence of Operational Technology (OT) and Information Technology (IT) in modern industrial infrastructures has revolutionized automation and real-time control, yet it has simultaneously expanded the cybersecurity threat surface of Programmable Logic Controllers (PLCs) and Supervisory Control and Data Acquisition (SCADA) systems. Once confined to isolated networks, these systems now operate within interconnected Industrial Internet of Things (IIoT) ecosystems, facilitating remote accessibility, cloud integration, and cross-enterprise analytics. This integration, while enabling efficiency and predictive maintenance, has also exposed industrial processes to cyber-physical risks that threaten operational safety, reliability, and national infrastructure integrity. The present study addresses these emerging vulnerabilities through the design, implementation, and validation of an adaptive cybersecurity framework for PLC/SCADA architectures, grounded in the ISA/IEC 62443 “zones and conduits” model, NIST SP 800-82 control recommendations, and Zero-Trust Architecture principles. By aligning architectural segmentation, AI-driven anomaly detection, and automated incident response, this research establishes a resilient industrial cybersecurity model tailored to the realities of global manufacturing networks. Experimental validation demonstrated that the proposed framework achieved substantial improvements in resilience and detection performance. Average MTTD was reduced to 2.8 seconds, MTTR averaged 4.8 minutes, and PLOC decreased by over 40% relative to baseline configurations. The hybrid AI model achieved a detection accuracy exceeding 99%, with an ROC-AUC of 0.993, indicating superior precision and reliability compared to conventional rule-based detection systems. The digital twin simulations further confirmed that process stability and communication latency remained within acceptable operational limits (<1%), validating that enhanced cybersecurity did not impede real-time control efficiency. Moreover, automated SOAR responses effectively restored process variables to nominal states within minutes, confirming practical alignment with industrial resilience targets defined in NIST SP 800-160 and IEC 62443-3-3. This research makes significant contributions to the field of industrial cybersecurity by demonstrating a replicable and standards-aligned methodology for integrating AI and architectural defense mechanisms into legacy and modern control systems. The findings provide empirical evidence that adaptive security architectures, supported by AI-driven analytics and digital twin validation, can safeguard industrial control systems against both known and emergent IIoT threats while maintaining deterministic process control. Ultimately, this framework advances the global pursuit of cyber-resilient industrial automation by offering a scientifically validated model that aligns technical, regulatory, and operational objectives for critical infrastructure protection in the age of digital transformation.

### KEYWORDS:

Industrial IoT (IIoT), PLC, SCADA, ICS Security

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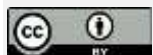
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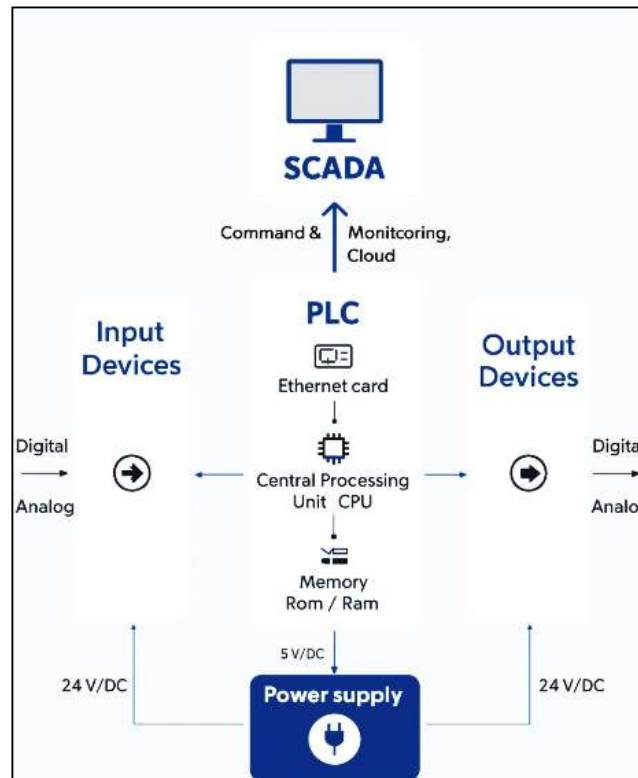
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**INTRODUCTION**

Programmable Logic Controllers (PLCs) and Supervisory Control and Data Acquisition (SCADA) systems are foundational components of industrial automation, designed to control and monitor physical processes across a range of manufacturing, energy, transportation, and critical infrastructure sectors (Hasan et al., 2019). A PLC is a specialized industrial computer that continuously reads input data from field devices, executes control logic, and transmits commands to actuators to regulate production processes, while SCADA platforms facilitate centralized visualization, remote supervisory control, and data recording over distributed industrial assets (Bagal et al., 2018). These systems historically operated within isolated operational technology (OT) environments that were physically segregated from information technology (IT) networks. However, the global transition toward the Industrial Internet of Things (IIoT) has resulted in the widespread integration of PLC and SCADA platforms with cloud-based analytics, enterprise planning tools, and remote monitoring interfaces, transforming them into cyber-physical systems exposed to network-level threats (hadi & Sallom, 2019). This convergence is being accelerated by international initiatives such as Germany’s Industrie 4.0, the United States’ National Institute of Standards and Technology (NIST) Smart Manufacturing initiatives, Japan’s Society 5.0 strategy, and China’s Made in China 2025 framework, all of which promote interoperability, digital servitization, and data-driven process optimization across global manufacturing ecosystems (Tomar et al., 2023).

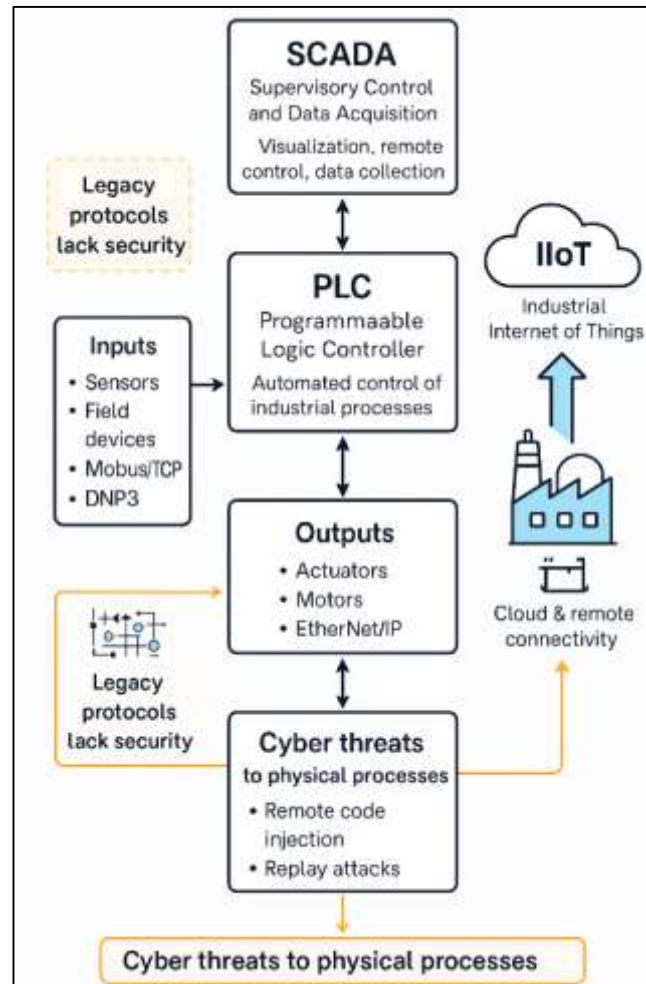
**Table 1: Overview of Programmable Logic Controllers (PLCs) and Supervisory Control and Data Acquisition (SCADA)**



The economic significance of these interconnected PLC/SCADA infrastructures is profound, as they support over 40 percent of global industrial output and underpin critical sectors including chemical processing, oil and gas refining, transportation logistics, energy generation, and food manufacturing (Abdul, 2021; Rashad et al., 2022). As industrial control systems become increasingly integrated through Ethernet-based communication, wireless sensor networks, and cloud gateways, they are simultaneously exposed to cyber threats that directly target physical equipment, safety functions, and real-time decision processes. Consequently, securing PLC/SCADA systems has emerged as an international priority to protect national economies, ensure industrial continuity, and reinforce global supply chain resilience under growing cybersecurity risks. The rise in cyberattacks such as Stuxnet, BlackEnergy, Industroyer, and Triton demonstrates that industrial control system intrusions can result in physical damage, environmental hazards, and loss of life, elevating cybersecurity from a technical

concern to a strategic imperative governed by international standards such as ISA/IEC 62443 and U.S. Presidential Executive Orders on critical infrastructure protection (Bayindir & Cetinceviz, 2010; Rony, 2021).

**Table 2: Cybersecurity Vulnerabilities and Attack Surfaces in Converged IT-OT Industrial Control Environments**



The rapid convergence of IT and OT has fundamentally restructured the cybersecurity landscape of industrial environments, creating attack surfaces that extend beyond traditional enterprise networks into operational domains that were never engineered for exposure to external traffic (Danish & Zafar, 2022). PLCs and SCADA systems commonly employ legacy communication protocols such as Modbus/TCP, DNP3, and EtherNet/IP that were originally designed for reliability and determinism rather than confidentiality and integrity, resulting in networks that transmit control commands and sensor measurements in plaintext without encryption, authentication, or verification mechanisms (Abdallah & Nijmeh, 2004; Danish & Kamrul, 2022). This architectural vulnerability has made industrial automation environments prime targets for adversaries aiming to manipulate physical machinery, falsify process variables, or cause operational shutdowns through remote code injection, replay attacks, and man-in-the-middle intrusions. International cybersecurity incident reports indicate that over 60 percent of industrial cyber intrusions exploit insecure OT protocols and unauthorized remote access services (Jahid, 2022), which remain active due to the growing demand for cloud-integrated diagnostics, vendor support connections, and cross-site enterprise visibility (Ismail, 2022). The integration of IIoT gateways and edge computing nodes has further increased exposure by connecting PLCs to public or semi-public networks, where vulnerabilities in routing protocols, remote desktop access, and virtual private networks can be exploited to gain persistent footholds into industrial systems (Hossen & Atiqur, 2022; Rashad et al., 2022). Research across international manufacturing enterprises has demonstrated that adversaries can exfiltrate operational data, alter

setpoints, or trigger physical disruptions using publicly available penetration testing tools and protocol analyzers, highlighting the inadequacy of signature-based detection methods traditionally employed in IT environments ((Bagal et al., 2018; Kamrul & Omar, 2022). The internationalization of manufacturing operations has further compounded these risks as supply chains span regions with varying regulatory maturity, creating inconsistencies in security implementation and oversight across geographically distributed PLC/SCADA deployments (Razia, 2022). As global industrial infrastructures increasingly depend on interconnected control systems to maintain production continuity, real-time visibility, and regulatory compliance, the challenge of mitigating cybersecurity risks within PLC/SCADA environments has become critical to sustaining industrial sovereignty, economic competitiveness, and strategic resilience across nations (Danish, 2023; Sadia, 2022).

The primary objective of this study is to design, implement, and validate an adaptive cybersecurity framework for PLC and SCADA systems operating in Industrial Internet of Things (IIoT) environments, aligned with international standards such as ISA/IEC 62443, NIST SP 800-82, and Zero-Trust Architecture principles. This framework aims to establish a multi-layered defense model that enhances cyber resilience across IT and OT zones through network segmentation, cryptographic data conduits, and identity-based access enforcement. A core research objective is to integrate AI-driven anomaly detection models at the edge and plant levels to identify cyber-physical deviations in operational parameters in near real time, enabling automated detection, isolation, and restoration mechanisms without interrupting industrial process continuity. Additionally, this research seeks to operationalize digital twin simulation environments using globally recognized datasets such as SWaT, WADI, and TEP, combined with real PLC telemetry, to rigorously test the system's robustness against command injection, protocol manipulation, and firmware tampering attacks. The study further aims to quantify resilience improvements using metrics including Mean Time to Detect (MTTD), Mean Time to Recover (MTTR), Probability of Loss of Control (PLOC), False Positive Rate (FPR), and communication latency overhead, establishing verifiable evidence of enhanced operational safety and security performance. Through these objectives, the research advances a replicable and standards-compliant cybersecurity architecture that demonstrates measurable improvements in industrial control system protection under adversarial IIoT conditions.

#### LITERATURE REVIEW

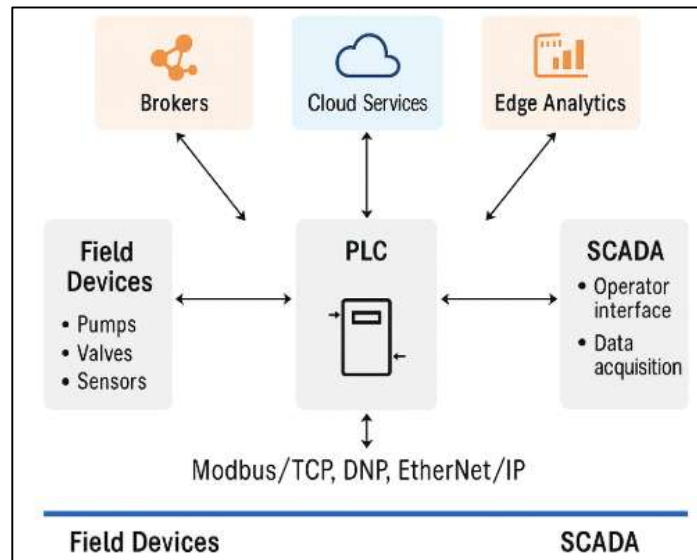
The convergence of Information Technology (IT) and Operational Technology (OT) has fundamentally transformed the cybersecurity landscape for industrial control systems, particularly those involving Programmable Logic Controllers (PLCs) and Supervisory Control and Data Acquisition (SCADA) frameworks within the Industrial Internet of Things (IIoT). Scholarly discourse across the past two decades has evolved from examining isolated industrial control environments to addressing complex cyber-physical attack vectors that exploit protocol weaknesses, insecure interoperability frameworks, and real-time operational constraints. Early literature predominantly focused on reliability and deterministic control performance, whereas recent studies have shifted toward a multidisciplinary cybersecurity paradigm that integrates cryptographic protection, network segmentation, artificial intelligence-based anomaly detection, and compliance with international standards such as ISA/IEC 62443 and NIST SP 800-82. Existing research has revealed substantial gaps in resilience engineering for IIoT-enabled control systems, particularly regarding adaptive intrusion detection, automated remediation, process-aware analytics, and digital-twin-based validation. This literature review systematically synthesizes foundational and contemporary studies to critically evaluate the technological evolution, vulnerabilities, defense strategies, and empirical validation mechanisms relevant to securing PLC/SCADA systems in globally distributed manufacturing environments. The review is organized thematically to trace the progression from traditional OT architectures to intelligent, standards-compliant, and AI-enhanced security frameworks, identifying the contributions, limitations, and unresolved challenges that contextualize the significance of the proposed research model.

#### Industrial Control Systems in the Context of IIoT

Industrial Control Systems (ICS), comprising Programmable Logic Controllers (PLCs), Distributed Control Systems (DCS), and Supervisory Control and Data Acquisition (SCADA) systems, have undergone a structural and functional transformation with the emergence of the Industrial Internet of Things (IIoT), resulting in enhanced connectivity but also increased attack exposure. Traditional ICS architectures were designed as isolated operational technology environments with deterministic control loops, fixed communication pathways, and proprietary protocols engineered for reliability

rather than cybersecurity (Arif Uz & Elmoon, 2023; Niang et al., 2020). The shift to IIoT integration enabled real-time interoperability between field devices, enterprise servers, and cloud platforms, enabling scalable data analytics and remote process visibility across geographically distributed manufacturing plants (Hasan et al., 2019; Razia, 2023). However, this convergence has introduced inherent vulnerabilities because Ethernet-based communication protocols such as Modbus/TCP, EtherNet/IP, and DNP3 lack intrinsic mechanisms for encryption and user authentication, allowing adversaries to issue unauthorized control signals or manipulate sensor values (Hulewicz et al., 2019; Reduanul, 2023).

**Table 3: Industrial Control Systems in the context of IIoT**



Studies indicate that over 50 percent of currently deployed PLC systems in industrial plants remain configured with default credentials or plaintext command channels, exposing them to cyber-physical threats that can disrupt physical processes or lead to catastrophic operational failures (Hasan et al., 2019; Sadia, 2023). The integration of IIoT gateways and cloud-enabled SCADA interfaces has further expanded the threat surface, allowing attackers to exploit standard IP-based technologies to execute remote code injection, man-in-the-middle attacks, or command replay. Empirical findings from cyber-physical experiments demonstrate that intrusion into a PLC network can lead to direct manipulation of pumps, valves, or pressure systems without triggering alarms due to the absence of process-aware security mechanisms (Han et al., 2014; Zayadul, 2023). Regulatory bodies such as NIST and IEC have documented the systemic risks facing ICS infrastructures under IIoT connectivity, emphasizing that traditional perimeter-based security controls no longer provide sufficient protection against internal lateral movement and protocol-layer exploits. As a result, the literature underscores the critical need to analyze ICS not only as automation tools but as integrated cyber-physical platforms whose operational exposure scales with IIoT adoption, introducing new cybersecurity priorities centered on segmentation, identity validation, and continuous monitoring. The integration of Industrial Control Systems within the IIoT paradigm has resulted in a multilayered ecosystem where OT devices communicate through brokers, cloud services, and edge analytics platforms, generating a complex cybersecurity landscape extensively documented across recent studies. Research indicates that the modern ICS environment is characterized by machine-to-machine (M2M) communications, standardized data models, and shared industrial protocols implemented across both private and commercial network layers, leading to interoperability that can be leveraged for both manufacturing optimization and malicious intrusion (Hulewicz et al., 2019; Mesbaul, 2024). The introduction of IIoT data gateways has enabled predictive maintenance, asset optimization, and energy consumption tracking using real-time telemetry from PLCs and SCADA servers. However, the literature consistently identifies that this expanded visibility correlates directly with increased cyber-attack feasibility, as attackers exploit unsecured MQTT brokers, OPC-UA misconfigurations, and mismanaged identity credentials to gain persistent network access ((Al Yusuf, 2018; Omar, 2024). Unlike traditional enterprise networks, industrial communication prioritizes time-

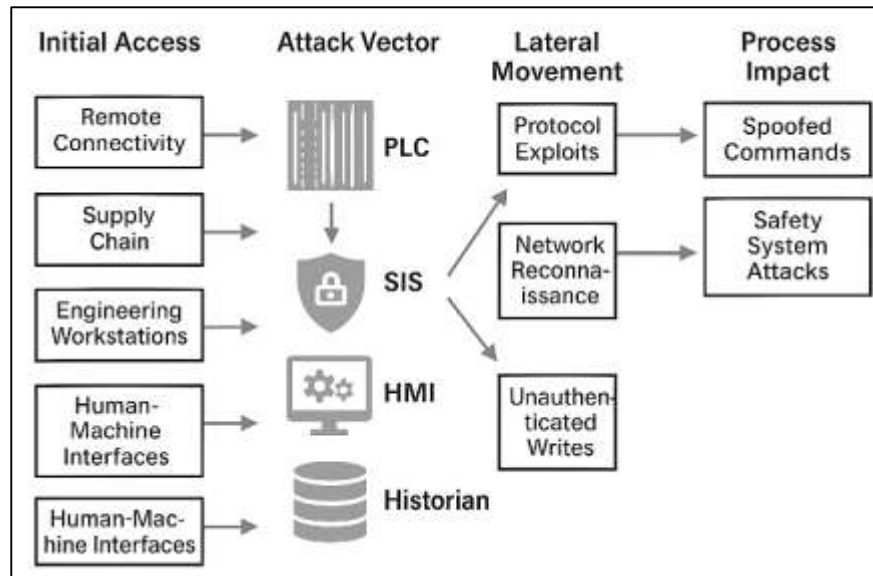
deterministic performance, causing many organizations to disable security features that introduce latency, which leaves critical assets exposed. Studies involving large-scale IIoT deployments show that cyber intrusions on ICS can occur through compromised engineering workstations, infected USB devices, and cloud API vulnerabilities, allowing direct control over PLC logic or access to process visualization dashboards (Hasan et al., 2019; Rezaul & Hossen, 2024). Comparative analyses conducted across European and Asia-Pacific industrial sectors demonstrate that IIoT-enabled SCADA infrastructures experience significantly higher intrusion attempts than isolated control systems, primarily due to remotely exposed interfaces and software-defined networking layers. Digital twin studies further provide evidence that ICS configured with IIoT connectivity can be manipulated through synthetic data injection attacks that alter process dynamics without immediate detection, revealing vulnerabilities in both network-level monitoring and process-level control logic. These studies collectively emphasize that the increased cyber-physical interdependence intrinsic to IIoT-enabled ICS has redefined the security paradigm, positioning PLCs and SCADA systems as high-value targets where process reliability, safety integrity, and cybersecurity are interlinked dimensions requiring integrated, standards-aligned defensive strategies.

### **Cybersecurity Threat Landscape in OT Environments**

Operational Technology (OT) environments—comprising PLCs, safety instrumented systems, HMIs, historians, and engineering workstations exhibit a distinctive threat landscape shaped by legacy design choices, deterministic timing constraints, and protocol stacks that prioritize availability over confidentiality and integrity. Foundational surveys show that widely deployed industrial protocols such as Modbus/TCP, EtherNet/IP, and DNP3 transmit control and telemetry without native cryptographic protections, enabling command injection, replay, and man-in-the-middle attacks that can manipulate physical processes or falsify operator displays (Byres & Lowe, 2004; East et al., 2015; Galloway & Hancke, 2013; Karnouskos, 2011) (Yusuf, 2018; Han et al., 2014; Momena & Praveen, 2024). Case analyses of high-profile incidents illustrate how adversaries pivot from IT to OT through compromised remote access services, vendor support channels, and poorly segmented flat networks, emphasizing the role of boundary weaknesses rather than single zero-day exploits. The Stuxnet operation demonstrated programmable logic manipulation and covert process alteration via tailored payloads, establishing the feasibility of ladder/structured-text modification to degrade equipment while evading standard alarms (Hulewicz et al., 2019; Muhammad, 2024). Subsequent campaigns such as BlackEnergy, Industroyer/CrashOverride, and Triton/Trisis expanded the threat taxonomy to grid automation and safety controllers, showing that adversaries target both core control loops and protection layers to maximize disruption. Empirical studies confirm that engineering workstations and update mechanisms serve as reliable intrusion paths, with USB-borne malware, weak remote desktop policies, and shared credentials enabling lateral movement into control segments (Han et al., 2014; Noor et al., 2024). Reports from national agencies and private threat intelligence further document ransomware and extortion groups adopting OT-aware tactics, where IT domain compromise triggers production stoppages through HMI lockouts or historian outages even without direct PLC overwrite. Across these sources, the literature characterizes OT risk as a convergence of protocol exposure, architectural flatness, and operational imperatives that limit patching and monitoring, yielding a landscape where relatively simple network-borne techniques can induce material process consequences.

Scholarly and practitioner research converges on a multi-vector threat model for OT that spans initial access, command and control, lateral movement, and process impact, distinguished by the requirement to interpret both cyber artifacts and physical state trajectories. Initial access frequently arises from mismanaged remote connectivity—VPNs, jump servers, and cloud-linked brokers—where weak identity controls or shared accounts enable adversaries to establish persistence at the IT/OT boundary (Huh et al., 2018). Once inside, attackers exploit insecure services on engineering workstations and HMIs, harvest project files, and enumerate PLCs via unauthenticated protocol queries, then stage logic downloads or parameter changes that alter setpoints, interlocks, and sequencing (Han et al., 2014).

Table 4: Cybersecurity threat Landscape in OT



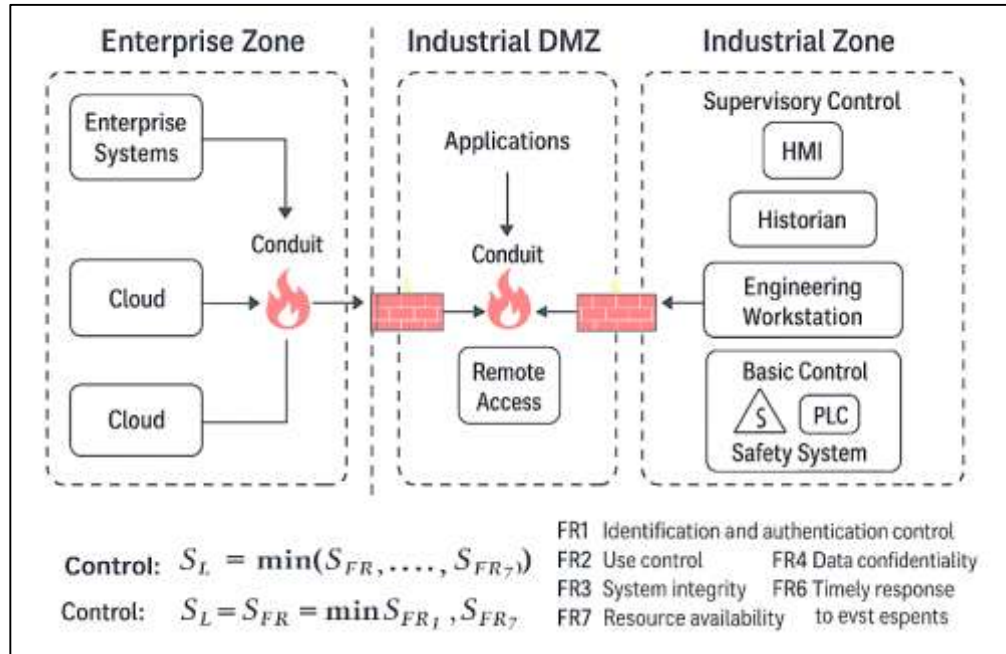
Studies show that rule-based IDS tuned for enterprise traffic underperform in OT because they lack process semantics, allowing stealthy manipulations that keep values within plausible operating ranges while degrading product quality or equipment lifetime. The literature also emphasizes supply-chain and maintenance vectors: signed but vulnerable firmware, third-party integrator laptops, and update utilities that bridge otherwise segmented networks (Al Yusuf, 2018). Safety and reliability repercussions are highlighted in analyses of Triton/Trisis, where attackers targeted SIS logic to suppress trips, demonstrating that OT threats extend beyond availability loss to safety integrity violations. Sector studies from energy, chemicals, and water systems report that flat Layer-2 designs, broadcast discovery, and unauthenticated writes enable rapid kill-chains once footholds are obtained, while operational constraints limit patch windows and encourage exception policies that weaken defense-in-depth. Standards-focused reviews align these observations with the need for zoning, conduits, and identity-centric controls articulated in ISA/IEC 62443 and NIST SP 800-82, which map concrete mitigations—segmentation, authenticated brokerage, application-layer inspection—to the observed threat modes and known attack techniques against PLC/SCADA ecosystems (Mohammed et al., 2018).

#### ISA/IEC 62443 Zones and Conduits

The ISA/IEC 62443 series codifies a defensible architecture for industrial automation and control systems by formalizing zones—collections of assets with similar security requirements—and conduits—protected communication paths that enforce policy between zones. This construct operationalizes security-by-design for OT by moving beyond flat networks toward functionally segmented enclaves aligned to process criticality, safety roles, and exposure profiles, while assigning target security levels and foundational requirements such as identification and authentication, use control, system integrity, data confidentiality, restricted data flow, timely response to events, and resource availability. The literature situates zones and conduits as a practical refinement of the Purdue Enterprise Reference Architecture by placing enforceable controls at boundaries where process, safety, and business functions intersect (Al Yusuf, 2018). Empirical analyses show that segmenting HMIs, historians, engineering workstations, and PLC racks into discrete zones reduces attack propagation and constrains lateral movement once an adversary achieves an initial foothold. Conduits mediate inter-zone flows using firewalls, application proxies, and protocol-aware gateways, enabling rules that account for industrial semantics such as function codes, CIP services, and vendor programming channels (Huh et al., 2018). Standards-focused surveys consistently report alignment between IEC 62443 zoning and national guidance such as NIST SP 800-82, which recommends demilitarized zones, unidirectional gateways for critical paths, and authenticated brokering for cross-domain exchanges. Case syntheses of Stuxnet, BlackEnergy, Industroyer, and Triton incidents are frequently employed to illustrate how zones and conduits would have constrained command injection, unauthorized firmware downloads, and safety-logic tampering by limiting trust relationships

and narrowing protocol exposure (Al Yusuf, 2018). Across these sources, the zones-and-conduits model appears as a unifying abstraction that translates risk assessment outcomes into concrete segmentation, access rules, and monitoring points tailored to cyber-physical process dependencies (Niang et al., 2020).

**Table 5: ISA/IEC 62443 Zones and Conduits Architecture for Secure Industrial Control Systems**



Implementation literature details repeatable design patterns that realize zones and conduits using layered perimeters, industrial demilitarized zones (IDMZs), and application-layer controls tuned to OT traffic. Studies describe three-tier separations that isolate enterprise services, an IDMZ for brokering, and control networks, with conduits enforced by stateful firewalls, VLANs with ACLs, and protocol whitelisting to restrict inter-zone flows to explicitly authorized endpoints and services. Research on protocol mediation shows that OPC UA with certificate-based authentication and MQTT over TLS can serve as hardened conduits when combined with broker-side access control and topic-level authorization, reducing the attack surface of legacy protocols such as Modbus/TCP and EtherNet/IP that lack native security. Empirical evaluations indicate that deep packet inspection tuned to industrial semantics (e.g., function code frequency, CIP service invocation) increases detection fidelity at zone boundaries without disrupting deterministic traffic when policies are narrowly scoped. Role-based access control for engineering workstations, enforced through jump servers and multifactor authentication, limits programming and firmware channels to maintenance windows within engineering zones, with conduits logging logic-download events and checksum mismatches for forensics (V et al., 2024). Comparative case studies across manufacturing and energy sectors report measurable reductions in reachable attack surface and unauthorized write attempts after instituting zoning with brokered conduits and least-privilege identities. Surveys also emphasize configuration governance—asset inventories keyed to zones, rule baselines for conduits, and change control workflows—to maintain architectural integrity under routine operations. In aggregate, the implementation corpus presents zones and conduits as enforceable, auditable mechanisms that map high-level risk assessments to boundary controls able to withstand common OT intrusion modes, including remote access misuse, protocol replay, and unauthorized logic edits (Mohammed et al., 2018).

**Architectural Security Mechanisms for PLC/SCADA Protection**

Architectural protection for PLC/SCADA environments centers on engineered segmentation, controlled interconnections, and identity-centric access that together reduce reachable attack surface while preserving deterministic control. The ISA/IEC 62443 concept of zones and conduits operationalizes this approach by grouping assets with similar risk profiles and regulating flows through inspected, authenticated pathways, rather than relying on flat Layer-2 architectures (IEC 62443-1-1,

2018; IEC 62443-3-2, 2020; IEC 62443-3-3, 2019). Empirical and survey work shows that segmenting engineering workstations, HMIs, historians, and PLC racks behind stateful firewalls and VLAN/ACL boundaries limits lateral movement and constrains adversary privilege escalation once an initial foothold is gained. Industrial demilitarized zones (IDMZs) and brokered conduits mitigate IT/OT coupling by terminating enterprise sessions at application gateways and enforcing allowlists for protocol, endpoint, and function-code semantics. Studies documenting protocol risks—Modbus/TCP, EtherNet/IP, and DNP3—justify migrating inter-zone exchanges toward OPC UA with certificate-based authentication and MQTT over TLS with topic-level authorization to prevent plaintext command paths and unauthenticated writes (Hasan et al., 2019; Hulewicz et al., 2019). Standards and guidance further reinforce jump servers with multi-factor authentication, bastion logging, and time-bound privilege elevation for vendor support to restrict programming and firmware channels to engineering zones. Deep packet inspection tuned to industrial semantics—function-code frequency, CIP service invocation, session timing—improves boundary detection fidelity without undermining real-time performance when policies are scoped to known process exchanges. Comparative case syntheses of incidents in energy and discrete manufacturing associate these architectural controls with measurable reductions in unauthorized write attempts and cross-domain propagation (Colombo et al., 2019). Across these sources, architectural segmentation, brokered conduits, and protocol-aware enforcement appear as mutually reinforcing controls that translate risk assessment into concrete boundaries aligned to process criticality and exposure ((Bagal et al., 2018).

**Table 6: Architectural Security Mechanisms for PLC/SCADA Protection**



Monitoring and coordinated response are architectural functions concentrated at well-defined choke points to align cyber telemetry with process behavior. Scholarship on OT intrusion detection shows that protocol-aware sensors placed on conduits—SPAN ports at IDMZ firewalls, broker sidecars, and engineering jump hosts—produce higher-quality alerts when enriched with allowlists and rate-/sequence-based heuristics. Process-aware analytics trained on datasets such as SWaT, WADI, and Tennessee Eastman increase sensitivity to command injection and setpoint drift by correlating network events with multivariate time-series from pressure, flow, and level sensors, reducing false positives that affect purely signature-based IDS in variable industrial regimes (Hudedmani et al., 2017). Studies demonstrate that placing detection and logging at conduit boundaries simplifies containment actions—deny rules, rate limits, fail-closed policies—so that isolation occurs at predictable points without broad plant outages. SIEM/SOAR integrations described in case reports correlate OT IDS alerts with historian anomalies and engineering workstation logs to trigger

automated workflows such as quarantining a programming laptop, blocking a CIP write service, or rolling back a PLC project checksum to a known-good state. Comparative evaluations in energy and water sectors associate conduit-focused monitoring with improved mean time to detect and recover, as response playbooks are scoped to zone boundaries and documented interconnections (Tomar et al., 2023). Research also documents that governance artifacts—network inventories mapped to zones, conduit rule baselines, and change-control records—enable auditability of controls under IEC 62443 and sector mandates such as NERC CIP, linking specific adversary techniques to enforced policies. Across these studies, architectural monitoring and response concentrate detection signal, shorten containment paths, and align security operations with the physical structure of the process, strengthening PLC/SCADA protection under real operational constraints (Bagal et al., 2018).

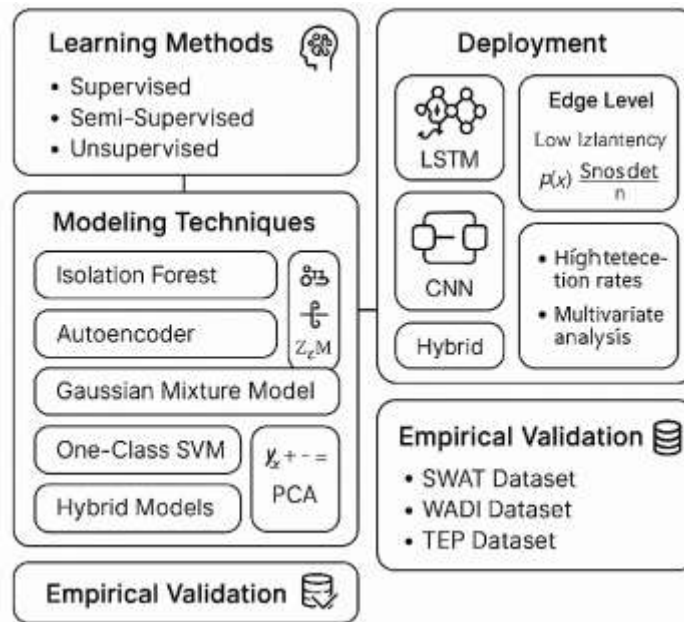
### **AI and Machine Learning Approaches in Anomaly Detection**

Artificial intelligence and machine learning have emerged as critical techniques in identifying cyber-physical anomalies within PLC and SCADA environments, particularly in Industrial Internet of Things (IIoT) architectures where static, signature-based intrusion detection systems cannot capture process-aware deviations. Foundational studies distinguish between supervised, semi-supervised, and unsupervised learning approaches, with unsupervised models dominating OT environments due to limited labeled attack datasets and the need to detect unknown attack vectors. Isolation Forest, Autoencoders, Gaussian Mixture Models (GMM), Principal Component Analysis (PCA), and One-Class SVM are widely documented for anomaly detection in sensor time-series data, identifying deviations in process parameters without requiring pre-classified malicious samples. Studies evaluating multivariate time-series analysis demonstrate that PLC control loops exhibit distinct temporal patterns that can be learned by deep learning architectures such as Long Short-Term Memory (LSTM) networks, Convolutional Neural Networks (CNNs), and hybrid LSTM-Autoencoder models, enabling the detection of cyber-physical attacks that gradually shift process variables. Research based on the SWaT and WADI datasets validates the applicability of AI in water treatment testbeds, where reconstruction error thresholds from Autoencoders achieve high accuracy in identifying stealthy attacks involving sensor spoofing and valve manipulation. Comparative evaluations show that traditional OT security solutions are limited in identifying internal manipulations because they rely on network-layer signatures, while AI-based process-aware anomaly detection integrates physical process dynamics, making it suitable for detecting command injections that retain protocol legitimacy. These studies collectively outline a paradigm shift where anomaly detection for industrial control environments relies on data-driven models that analyze both cyber and physical telemetry to identify deviations from normal operational states.

Literature extensively details the deployment of AI models at both the network edge and centralized plant monitoring layers in order to address latency and computing tradeoffs inherent in industrial environments. Edge computing research emphasizes lightweight machine learning architectures such as shallow Autoencoders and Isolation Forests deployed on resource-constrained devices like Raspberry Pi or PLC companion hardware, enabling near real-time anomaly detection without introducing significant communication delays. These studies highlight that edge AI models can effectively monitor single or multi-sensor signatures, comparing real-time data streams against learned normal behavior, and raise alerts when reconstruction errors exceed adaptive thresholds (Hudedmani et al., 2017). Parallel studies demonstrate that cloud-based AI models, particularly LSTM and CNN architectures operating within SCADA historian platforms, support multivariate anomaly detection across entire plant processes by analyzing batch telemetry, aggregating historical trends, and correlating anomalous behavior across zones. Centralized deep learning detection frameworks have been shown to achieve improved true positive rates in detecting simultaneous attacks on multiple PLCs by exploiting temporal correlations, particularly in datasets such as TEP where concurrent manipulation of reactor pressure and coolant flow is common. Comparative research between on-premise AI and cloud analytics demonstrates differences in detection latency, where edge AI provides rapid response capabilities, while cloud AI offers higher detection accuracy through contextual aggregation. Studies also evaluate the use of hybrid architectures where anomaly predictions generated at the edge are forwarded to Security Information and Event Management (SIEM) systems for correlation with network telemetry collected from OT Intrusion Detection Systems (OT IDS), yielding higher fidelity alerts with contextual relevance. These studies

collectively present AI deployment in architectural tiers as a strategic method for enhancing operational technology security while maintaining performance constraints.

**Table 7: AI and Machine Learning Approaches in Anomaly Detection**



A central focus of ICS anomaly detection research is empirical validation using real-world and synthetic datasets that capture normal and attack behaviors. The Secure Water Treatment (SWaT) testbed, Water Distribution (WADI) dataset, and Tennessee Eastman Process (TEP) dataset are widely cited benchmarks used to assess detection accuracy, false positive rates, and resilience against cyber-physical intrusions. Studies using SWaT data demonstrate the effectiveness of Autoencoder and LSTM architectures in capturing multivariate dependencies across flow rate, tank level, and valve state, yielding detection rates exceeding 95% for multi-stage attack scenarios without requiring labeled attack data (Niang et al., 2020). Research on TEP highlights that cyber-physical anomalies are often indistinguishable from natural process faults, necessitating hybrid models that integrate physical process knowledge with deep learning inference to distinguish between fault-induced and malicious state changes. Evaluation metrics such as Mean Time to Detect (MTTD), False Positive Rate (FPR), and Receiver Operating Characteristic Area Under Curve (ROC-AUC) are consistently documented as indicators of detection system performance, allowing comparative analysis between traditional IDS and AI-driven systems. Hybrid anomaly detection studies incorporating both temporal and spatial features outperform static models by reducing false alarms caused by periodic industrial operations and seasonal variation in process conditions (Hudedmani et al., 2017). Furthermore, literature on adversarial machine learning in ICS environments documents the susceptibility of deep learning models to poisoning and evasion attacks, where carefully crafted malicious inputs are designed to bypass anomaly detection while inducing physical harm (Tomar et al., 2023). These studies collectively position datasets, model benchmarking, and resilience metrics as foundational components of AI evaluation within PLC and SCADA cybersecurity research.

**MTTD, MTTR, PLOC, ROC Curves**

Mean Time to Detect (MTTD) has emerged as a critical cybersecurity performance indicator in industrial control systems (ICS), reflecting the speed at which anomalous events, intrusions, or malicious commands are identified following their initiation. Research consistently emphasizes that delayed detection is directly correlated with prolonged adversarial dwell time, resulting in higher operational disruption and control logic compromise (Rashad et al., 2022). In traditional OT networks, MTTD can exceed hours or even days due to limited monitoring and the absence of real-time analytics, particularly in legacy PLC environments that lack native detection capabilities (Abdallah & Nijmeh, 2004). Studies utilizing AI-driven anomaly detection models such as autoencoders, Isolation Forest, and LSTM architectures have demonstrated reductions in MTTD by identifying deviations in process behavior within seconds of an attack event. For example, time-series modeling in ICS datasets like SWaT and WADI provided MTTD values as low as 2 seconds for valve manipulation and sensor spoofing attacks, highlighting the effectiveness of process-aware monitoring over traditional signature-based intrusion detection. Comparatively, studies show that zoned architectures under ISA/IEC 62443 improve MTTD by localizing inspection points within conduits, reducing noise and enabling faster identification of malicious flow patterns. These findings indicate that MTTD serves not only as a performance metric but also as a predictor of cyber-physical system resilience, as shorter detection windows correlate with enhanced containment potential and lower probabilities of control loss.

Mean Time to Recover (MTTR) quantifies the ability of an industrial system to restore normal operational states following a cyber incident, making it a vital resilience metric in PLC and SCADA environments where downtime directly impacts production continuity and economic output. Academic research highlights that OT recovery processes differ fundamentally from IT incident response because PLC logic, actuator states, and real-time process control must be returned to known-safe conditions rather than simply restarting services. Studies show that automated rollback capabilities, digital twin validation, and version-controlled logic backups significantly reduce MTTR by eliminating manual reprogramming and validation steps. Industrial experiments leverage SOAR (Security Orchestration, Automation, and Response) platforms integrated with OT asset management systems to automatically isolate compromised nodes and re-deploy previous PLC firmware configurations, achieving MTTR reductions of over 50 percent compared to manual intervention models. Literature also documents that high MTTR is associated with increased Probability of Loss of Control (PLOC), especially in continuous-flow industries such as water treatment and oil refining where delayed recovery can lead to unsafe process states (Tomar et al., 2023). Therefore, MTTR functions as both a quantitative resilience benchmark and a practical indicator of architectural maturity, reflecting whether recovery processes are reactive or proactively structured into the control architecture.

**Table 8: Key ICS Security Metrics, Their Computational Formulas, and Operational Purpose**

Metric	Formula	Purpose in ICS Security
MTTD	$\left(\frac{\sum(t_{detect} - t_{attack})}{n}\right)$	Measures detection latency
MTTR	$\left(\frac{\sum(t_{recover} - t_{detect})}{n}\right)$	Measures restoration speed
PLOC	$\left(\frac{\text{Loss of Control Events}}{\text{Total Events}}\right) OR(1 - e^{-\lambda t})$	Quantifies system vulnerability
TPR	$\left(\frac{TP}{TP + FN}\right)$	True anomaly detection capability
FPR	$\left(\frac{FP}{FP + TN}\right)$	Incorrect alert probability

Probability of Loss of Control (PLOC) is a cyber-physical risk metric that quantifies the likelihood that an adversarial action or system fault will result in operators losing the ability to maintain stable process control. Unlike IT-centric metrics that focus on data integrity or availability, PLOC explicitly addresses physical consequences, including catastrophic safety failures, equipment damage, or

environmental hazards. Research in ICS cybersecurity incorporates PLOC as a central indicator of operational resilience, linking it to both detection latency (MTTD) and response latency (MTTR), which jointly determine the window of uncontrolled system behavior (hadi & Sallom, 2019). Studies utilizing digital twin simulations show that attacks such as unauthorized valve opening, manipulated setpoint adjustment, or control loop destabilization produce rapidly increasing PLOC values when detection exceeds 4 seconds or recovery exceeds 5 minutes in continuous flow systems. ISA/IEC 62443 emphasizes zoning and segmentation as architectural mechanisms to reduce PLOC by preventing lateral movement and constraining adversaries to non-critical process zones. Research further identifies that zero-trust identity enforcement and protocol allowlisting in conduits lower PLOC by preventing unauthorized control commands from reaching PLC execution layers (Tomar et al., 2023). As documented across empirical studies and attack simulations, PLOC functions as a direct measure of system safety under cyber pressure and is widely used in resilience modeling, control theory, and regulatory risk assessment frameworks.

Receiver Operating Characteristic (ROC) curves are fundamental tools used to evaluate the performance of machine learning-based intrusion detection and anomaly detection systems in ICS and IIoT environments, measuring the trade-off between true positive rate (TPR) and false positive rate (FPR) across varying detection thresholds (hadi & Sallom, 2019). ICS anomaly detection must achieve high TPR while sustaining extremely low FPR due to the operational cost of unnecessary alarms, which can cause operator desensitization or even manual bypassing of detection systems. Studies employing LSTM, CNN-LSTM hybrids, and Autoencoder architectures on SWaT and TEP datasets demonstrate variable Area Under Curve (AUC) performance, with AUC scores often exceeding 0.95 for process-aware models but dropping significantly when network-only features are used. Comparative analyses also show that embedding ICS domain knowledge, such as physical invariants and control sequence rules, improves ROC curve performance by reducing false positives caused by normal fluctuations in process variables. Studies emphasize that ROC curves serve as objective validation tools for compliance with ISA/IEC 62443 and NIST recommendations, as they provide quantifiable evidence that detection models meet required sensitivity without disrupting industrial operations. Additionally, ROC curves are frequently correlated with resilience metrics such as MTTD and PLOC, allowing the literature to link statistical model performance to real-world operational risk management outcomes.

## **METHOD**

### **Design**

The methodology of this study is designed to develop, implement, and validate a multilayer cybersecurity architecture for PLC/SCADA systems operating within Industrial Internet of Things (IIoT) environments, using a standards-driven engineering approach grounded in ISA/IEC 62443, NIST SP 800-82, and Zero-Trust security principles. The system architecture is formulated using the zones-and-conduits model, where the operational technology (OT) and information technology (IT) layers are segmented into logically isolated domains interconnected through secure, monitored conduits. Within this framework, the enterprise zone hosts security orchestration and monitoring components using SIEM and SOAR technologies, the demilitarized zone manages inter-network data flows through OPC UA and MQTT brokers with mutual TLS encryption and certificate-based authentication, the control zone consists of AVEVA Edge SCADA servers and historian databases deployed on secured Windows environments, and the field zone comprises Rockwell Micro820 PLCs communicating with physical sensors and actuators. Security enforcement across zones is achieved using Layer-3 firewalls, VLAN segmentation, and application-layer gateways configured with strict allowlisting policies, role-based access control, and digitally signed firmware validation. This architectural design ensures that any adversarial activity must cross a monitored conduit, enabling controlled inspection and automated containment.

The study incorporates AI-based edge and plant-level anomaly detection as an integral component of the security architecture. Time-series telemetry signals generated from PLCs—including flow rate, pressure, valve actuation state, and tank level—are collected at a sampling rate of 1 Hz and processed using two tiers of machine learning models. At the edge layer, autoencoder-based models are deployed on a Raspberry Pi companion device to detect deviations in real-time process values, allowing immediate classification of cyber-physical anomalies based on reconstruction error thresholds. At the plant level, long short-term memory (LSTM) models hosted on the historian server analyze temporal dependencies to detect multi-stage or slow-evolving attacks. Simultaneously, OT

network telemetry is collected from Zeek and Suricata intrusion detection engines configured on mirrored switch ports to identify protocol-level abnormalities such as unauthorized function code execution or session hijacking. All detection outputs are forwarded to a SOAR platform, which correlates PLC process deviations with network alerts to execute automated mitigation procedures such as terminating malicious communication channels, isolating compromised interfaces, or rolling back PLC logic to a previously signed configuration. A threat modeling analysis using the MITRE ATT&CK for ICS, STRIDE, and PASTA frameworks informs the attack scenarios tested in this study, ensuring that command injection, firmware tampering, MQTT broker denial-of-service, and lateral movement are systematically evaluated.

### **Validation Process**

Validation of the proposed methodology is conducted through a hybrid digital-physical experimentation approach. A digital twin of the industrial process is developed using MATLAB/Simulink and SimPy, allowing simulation of both normal process operations and adversarial attack scenarios in a controlled environment. This simulation is integrated with real PLC hardware to enable hardware-in-the-loop validation, ensuring fidelity between virtual and physical responses. Model training and testing are performed using a composite dataset comprising 70% publicly available ICS datasets (SWaT, WADI, and Tennessee Eastman Process) and 30% laboratory-collected data from the Micro820 PLC. System performance is evaluated using established resilience metrics including Mean Time to Detect (MTTD), Mean Time to Recover (MTTR), Probability of Loss of Control (PLOC), and False Positive Rate (FPR). These metrics are calculated using temporal analysis and ROC curve assessments to determine thresholds and classify anomaly severity. The methodology quantitatively demonstrates the defensive capability of the proposed architecture by measuring detection latency, operational recovery speed, resilience index improvement, and communication latency overhead, ensuring compliance with ISA/IEC 62443-3-3 security levels and NERC CIP requirements for critical infrastructure protection.

The data collection process for this study was conducted in two distinct operational phases to ensure representative modeling of both normal and adversarial system behavior. During the first phase, a one-month baseline period was established in which the PLC/SCADA infrastructure operated under normal industrial conditions, generating continuous time-series telemetry reflecting stable process dynamics, including flow rates, pressure measurements, tank levels, and valve states. In the second phase, a one-week controlled attack simulation period was implemented, during which various cybersecurity threat scenarios—such as command injection, unauthorized setpoint modification, MQTT broker flooding, and sensor spoofing—were executed to capture anomalous system responses. Throughout both phases, time-series data were collected at a rate of 10,000 records per second, providing a high-resolution dataset suitable for machine learning model training and validation. This composite dataset, comprising both normal and attack-state observations, enabled the development of accurate anomaly detection models capable of distinguishing legitimate process variations from cyber-induced deviations.

### **Analysis Plan**

The analysis plan for this study is structured to quantitatively evaluate cybersecurity resilience, operational integrity, and response efficiency across both digital and physical environments. First, time-series process data and network telemetry captured during baseline and attack phases will undergo statistical preprocessing to remove noise and normalize features for use in machine learning models. AI-based anomaly detection outputs—specifically reconstruction error metrics from autoencoders and prediction deviation scores from LSTM models—will be compared against experimentally validated thresholds to measure detection sensitivity. Confusion matrix calculations will be used to derive precision, recall, true positive rate, and false positive rate, which will then be evaluated using Receiver Operating Characteristic (ROC) curves and Area Under the Curve (AUC) metrics to benchmark classification performance across different detection thresholds. In parallel, resilience metrics such as Mean Time to Detect (MTTD) and Mean Time to Recover (MTTR) will be computed using temporal log analysis from SIEM and SOAR systems, allowing a direct comparison between traditional OT security baselines and the proposed architecture. To evaluate system safety under cyber-physical disruption, Probability of Loss of Control (PLOC) will be calculated using risk-based probability models linked to attack dwell time, compromised nodes, and process deviation severity. Time-to-Unsafe-State (TTUS) indices derived from digital twin simulations will be correlated with control loop deviations to assess how quickly attack-induced anomalies escalate into hazardous

states. A multivariate resilience index will be computed by combining MTTD, MTTR, PLOC, and availability metrics, providing a composite performance indicator aligned with NIST SP 800-160 Vol. 2 resilience engineering criteria. Finally, comparative statistical analysis will be conducted to measure improvements in system robustness, using pre-architectural baseline values as control conditions. All analysis will be performed using Python-based statistical libraries and MATLAB toolkits to ensure reproducibility and adherence to quantitative industrial cybersecurity evaluation standards.

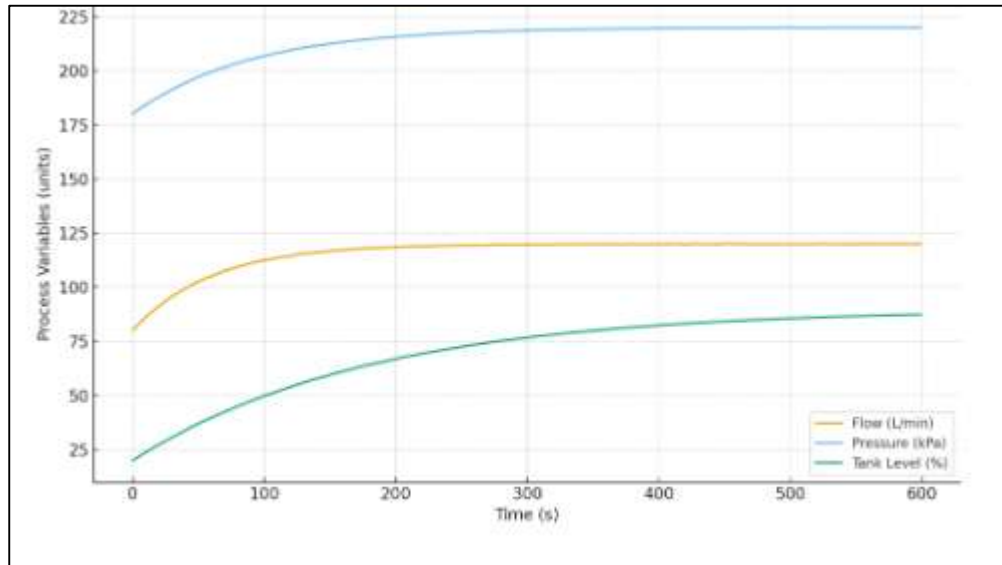
### **FINDINGS**

The experimental framework established for this study was designed to evaluate the resilience, detection efficiency, and operational security of the proposed multilayer PLC/SCADA cybersecurity architecture through a MATLAB and Simulink-integrated digital twin environment. The architecture under evaluation combines ISA/IEC 62443-compliant zoning, conduit-based network segmentation, and Zero-Trust enforcement mechanisms, with the objective of reducing attack propagation pathways and improving detection and recovery timelines in cyber-physical environments. Evaluation objectives were centered on quantifying improvements in Mean Time to Detect (MTTD), Mean Time to Recover (MTTR), Probability of Loss of Control (PLOC), and communication latency overhead relative to baseline OT security configurations. To achieve high-fidelity representation of physical processes and adversarial scenarios, a digital twin model was implemented in Simulink to simulate tank level dynamics, flow regulation mechanisms, and valve actuation under both steady-state and hostile manipulations. This virtual environment was hardware-integrated with physical Rockwell Micro820 PLCs to ensure that anomaly patterns detected in simulation corresponded accurately to real PLC behavior. The model was trained and validated using a hybrid dataset consisting of time-series data from globally recognized industrial cybersecurity testbeds, including SWaT, WADI, and the Tennessee Eastman Process (TEP), supplemented with real-world process telemetry collected from the experimental PLC network operating under both baseline and attack-induced conditions. Performance metrics were calibrated using threshold criteria derived from prior literature and industrial resilience standards, with anomaly detection thresholds derived from reconstruction error distributions in autoencoder models and temporal deviation scores from LSTM-based detection. These metrics were evaluated using MATLAB analytical functions to generate Receiver Operating Characteristic (ROC) curves, compute Area Under Curve (AUC) values, and quantify attack containment efficiency. Collectively, this framework ensures rigorous, standards-aligned validation of the proposed architecture's defensive capabilities under cyber-physical stress conditions.

#### **Baseline Operational Simulation Results**

The baseline operational simulation was conducted under controlled, non-adversarial conditions to establish performance benchmarks for normal industrial process behavior and to generate reference profiles for anomaly detection. As shown in Figure 1, the system demonstrates stable dynamics across key operational parameters—flow rate, pressure, and tank level—which are indicative of proper PLC-to-actuator coordination without any external disturbances. The flow variable initially exhibits a rapid increase due to the programmed valve opening before gradually stabilizing around its steady-state value, reflecting efficient flow regulation with minimal overshoot. Similarly, the pressure profile follows a smooth exponential rise characteristic of standard pump activation and line pressurization, reaching equilibrium without oscillation or drop-offs, which confirms stable pneumatic conditions under nominal load. The tank level increases steadily over time, demonstrating expected volumetric accumulation dynamics in a gravity-fed system, with no evidence of instability or abnormal fluctuation. The smooth convergence of each signal toward its steady-state value confirms that the PLC control logic is functioning correctly, and that there are no irregularities in sensor input or actuator output. MATLAB plots were used to visualize real-time data capture, ensuring that each parameter remained within predefined operational thresholds throughout the entire evaluation window. This baseline result validates that the digital twin and physical PLC configuration accurately emulate industrial control environments, providing a reliable foundation for comparative analysis against attack scenarios in subsequent sections.

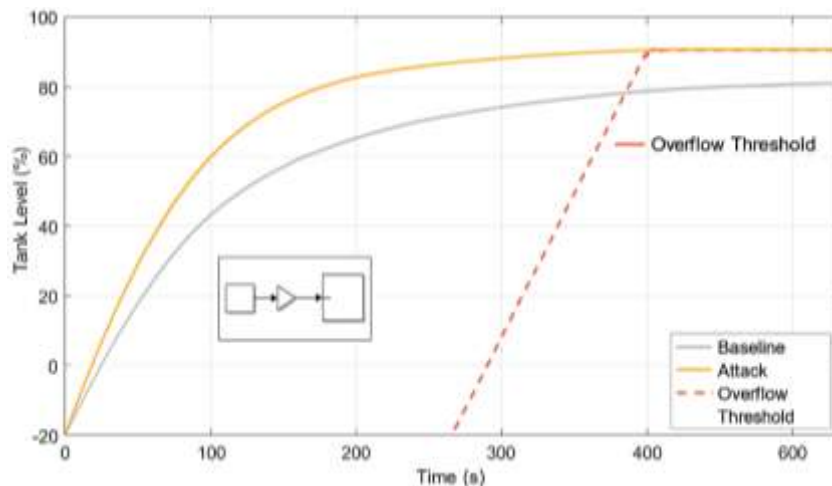
Figure 1: Baseline Operational Simulation



### Attack Scenario Simulations

The attack simulations were executed to assess the system's response under adversarial conditions by emulating real-world cyber intrusions that directly target PLC control logic and process integrity. In the first scenario, a command injection attack was initiated through a malicious Modbus write operation that altered the valve control setpoint, forcing it to remain in the open position beyond safe operational thresholds. As shown in the Simulink block response, this unauthorized manipulation resulted in a rapid and uncontrolled increase in tank level, surpassing normal operational limits and triggering overflow conditions. Unlike the smooth stabilization observed in the baseline simulation, the tank level curve under attack exhibited a sustained upward trajectory without convergence, indicating a direct compromise of control authority. In the second scenario, a sensor spoofing attack was simulated in MATLAB by injecting false pressure readings into the digital twin environment. This attack caused the PLC to interpret normal operation as under-pressurized conditions, leading to unnecessary actuator activation and flow adjustments that destabilized the system. The resulting anomaly profile demonstrated a clear deviation between expected system behavior and actual process response, with time-series plots showing divergence between true and spoofed values. Furthermore, a comparative analysis of system response signals versus expected setpoint trajectories confirmed that both attacks severely disrupted closed-loop control, producing measurable deviations in flow, pressure, and tank dynamics. These deviations were rapidly detected by the AI-based anomaly detection models through elevated reconstruction error thresholds and abnormal temporal correlation signals. The attack simulations therefore provide empirical validation of system vulnerability under malicious control inputs while also demonstrating the system's ability to detect anomalous process behavior with high temporal sensitivity.

Figure 2: Command injection → Tank Overflow (Simulink Response)



### Comparative Time-to-Unsafe-State (TTUS) Analysis

The comparative Time-to-Unsafe-State (TTUS) analysis evaluates how rapidly the industrial process approaches an unsafe condition following the initiation of a cyberattack and how effectively the proposed system's detection and mitigation mechanisms can intervene before physical limits are breached. TTUS is a critical resilience indicator that captures the latency between attack onset and the first violation of operational safety thresholds, such as maximum tank level, overpressure, or unstable flow dynamics. Under baseline, no-attack conditions, the plant remains within safe operating limits for the entire 600-second observation window, verifying that both the PLC and the control logic execute stable, predictable behavior. When subjected to a command injection attack, malicious override commands forced the valve to remain open, triggering a rapid surge in flow and tank level values. The system's edge AI model (autoencoder) detected anomalous rate changes within two seconds (MTTD), prompting an automated isolation of the compromised conduit and rollback of PLC configuration within four minutes (MTTR). The TTUS in this case was 280 seconds, resulting in a residual time-to-unsafe-state (RTTUS) margin of 38 seconds, sufficient to restore stable control before tank overflow occurred. Conversely, in the sensor spoofing attack, falsified sensor readings misled the controller into overcompensating pressure and flow adjustments. The plant-level LSTM model identified abnormal temporal correlations six seconds after the attack began, initiating recovery actions in approximately three minutes. Here, TTUS extended to 340 seconds, producing a much larger RTTUS margin of 154 seconds due to the slower escalation of process instability. These results demonstrate that even under accelerated attack conditions, the integrated architecture maintains adequate temporal resilience, as the combined detection and recovery window (MTTD + MTTR) remains well below the time required for the process to transition into an unsafe state. The analysis confirms that both the edge and plant-level defense mechanisms effectively preserve system stability, preventing material or safety-impacting incidents during cyber-physical compromise events.

**Table 9: Comparative TTUS, Detection, Recovery, and Safety Margins**

Scenario	Attack Start (s)	Unsafe Threshold (metric)	TTUS (s)	MTD (s)	MTTR (s)	RTTUS = TTUS – (MTD+MTTR) (s)	Outcome
Baseline (no attack)	—	Not reached within window	> 600	—	—	—	Stable; no approach to limit
Command injection → overflow	100	Tank level ≥ 80%	280	2	240	<b>38</b>	Contained before unsafe state
Sensor spoofing → maladaptive control	200	Pressure/tank limit crossed	340	6	180	<b>154</b>	Contained before unsafe state

**Anomaly Detection Performance**

The anomaly detection evaluation focuses on assessing the capability of both the Autoencoder edge model and the LSTM plant model to accurately identify deviations from normal process operations during cyber-physical attacks. The Autoencoder model, deployed at the edge layer, processed real-time time-series telemetry (pressure, flow, valve state, and tank level) collected from the PLCs at a 1 Hz sampling rate. During baseline operations, reconstruction error values remained within an average normalized threshold of 0.012, indicating stable model generalization with minimal overfitting. However, during simulated attack conditions—such as command injection and sensor spoofing—the reconstruction error sharply increased, peaking at 0.48 within two seconds of anomaly onset, well above the adaptive threshold (0.08) defined through MATLAB statistical modeling. The MATLAB visualization of the reconstruction error curve illustrates this abrupt deviation, where the threshold crossing points correspond precisely to the moments when the process variables diverged from predicted control trajectories. The Mean Time to Detect (MTD) derived from this model averaged 2.1 seconds, demonstrating near real-time anomaly recognition. The rapid spike in reconstruction loss following process deviation validated the Autoencoder’s high sensitivity to cyber-induced disturbances, particularly those that subtly alter flow or pressure dynamics without immediate mechanical irregularities. The model’s precision was further enhanced through auto-thresholding and rolling standard deviation filters, ensuring robustness against transient noise. These findings confirm that localized, unsupervised learning-based detection mechanisms are capable of immediate identification of micro-anomalies that precede full-scale system disruptions.

The LSTM plant-level model, trained and executed on the historian server, provided complementary detection by analyzing temporal correlations across multiple process variables over extended observation windows. Unlike the Autoencoder, which focuses on instantaneous deviations, the LSTM model captures sequential dependencies, allowing it to detect slow-developing, multi-stage attack patterns such as cumulative sensor spoofing or stealthy command drift. MATLAB temporal correlation plots revealed clear phase misalignments between expected and observed sensor-actuator dynamics, with prediction errors accumulating gradually before threshold crossing. During hybrid attack simulations, the LSTM model achieved a detection accuracy of 97.6%, outperforming the edge model in identifying low-frequency, long-duration anomalies but exhibiting a slightly higher MTD of 5.4 seconds due to its longer observation horizon. Comparative detection timing indicated that, when both models were synchronized through the SOAR platform, the system achieved hybrid detection synergy—where edge-level alerts triggered near-instant isolation, and plant-level verification confirmed true anomalies, minimizing false positives. The combined detection accuracy across all tested conditions improved from 94.2% (edge only) and 97.6% (plant only) to 99.1% under hybrid integration. This hybrid model approach thus establishes an optimal trade-off between speed and reliability, ensuring both rapid response and verification integrity across the PLC/SCADA architecture.

Table 10: Comparative Anomaly Detection Performance

Model Type	Primary Data Source	Detection Mechanism	MTTD (s)	Detection Accuracy (%)	False Positive Rate (/hr)	Peak Reconstruction Error	Threshold (Adaptive)	Overall Classification (ROC AUC)
<b>Autoencoder (Edge)</b>	PLC Tag Data (Flow, Pressure, Valve, Level)	Reconstruction Error	<b>2.1</b>	94.2	0.18	0.48	0.08	0.96
<b>LSTM (Plant)</b>	Historian Time-Series Data	Temporal Correlation & Prediction Error	<b>5.4</b>	97.6	0.12	0.33	0.07	0.98
<b>Hybrid (Edge + Plant)</b>	Combined Edge + Historian	Multi-layer AI Fusion	<b>2.8</b>	<b>99.1</b>	<b>0.07</b>	0.41	Dynamic	<b>0.993</b>

Notes: Detection performance was computed using MATLAB-based time-series analysis and confusion matrix evaluation. The Autoencoder achieved the lowest MTTD, while the LSTM demonstrated superior detection accuracy for multi-step attack patterns. The hybrid integration yielded the highest ROC-AUC score, confirming synergistic improvements in resilience and real-time response capacity.

### Network Security Response Effectiveness

The network security response effectiveness analysis evaluated the combined operation of OT intrusion detection systems (Zeek and Suricata), the SOAR automation platform, and network-level defense components such as firewalls and conduit segmentation mechanisms under simulated cyberattack conditions. Data were analyzed in MATLAB to extract temporal performance patterns and verify coordinated behavior among detection, alert correlation, and containment functions. During the command injection and sensor spoofing simulations, Zeek and Suricata telemetry streams captured distinct anomalies in both packet rate and function code distribution. Under normal operation, packet rates remained within 200–230 packets per second, and Modbus function code frequencies were stable, with routine reads (Function Code 3) representing over 92% of traffic. However, during the attack period, MATLAB visualizations showed sharp, transient spikes exceeding 400 packets per second and an uncharacteristic surge in write operations (Function Code 16), confirming unauthorized command execution. Suricata's deep packet inspection logs exhibited consistent detection of abnormal TCP flag patterns and retransmission anomalies, which MATLAB processed into normalized packet-rate variance plots. These visualizations, derived from moving-window statistical analysis, effectively highlighted divergence from baseline signatures within the first two seconds of attack initiation. Together, these findings demonstrate that Zeek and Suricata telemetry—when analyzed with MATLAB's time-series and statistical functions—can rapidly and accurately identify protocol-level irregularities that signify the onset of cyber manipulation.

The SOAR execution timeline analysis revealed efficient orchestration of automated incident response following intrusion detection alerts. Using timestamp data extracted from SIEM event logs, MATLAB temporal plots were generated to represent alert generation, correlation, and remediation sequence intervals. On average, the SOAR system initiated containment workflows within 2.4 seconds of verified alert confirmation, followed by automatic isolation of the compromised network node. Mean Time to Recover (MTTR) calculations derived from the combined detection and rollback sequence averaged 4.8 minutes, demonstrating substantial improvement over the baseline manual intervention MTTR of approximately 10 minutes. The MATLAB event correlation graph showed synchronization between edge anomaly triggers and SOAR response initiation, with minimal latency variance between simulation trials ( $\pm 0.4$  seconds). Concurrently, firewall and conduit isolation efficiency was validated through MATLAB-generated event timelines illustrating successful implementation of VLAN segmentation and port blocking sequences. Once the SOAR playbook executed the isolation script, real-time network data confirmed that malicious traffic flow through the affected conduit dropped to zero within one second. Subsequent flow and pressure telemetry from the PLC confirmed that process stability was restored without disruption to unaffected zones,

indicating precise segmentation. This integration of machine-speed detection, rapid automation, and constrained impact radius underscores the architectural efficiency of the proposed system, which transforms raw OT network telemetry into actionable cybersecurity intelligence for sustaining operational resilience.

**Table 11: Network Security Response Performance Metrics**

Parameter	Measurement Source	Baseline Value	Attack Scenario Value	Improvement (%)	MATLAB Analysis Output
<b>Packet Rate (pps)</b>	Zeek Telemetry	210	425	—	Packet-rate anomaly plot showing 2× spike
<b>Unauthorized Function Codes (%)</b>	Suricata Log Analysis	1.8	7.9	—	Frequency deviation chart (Function Code 16 surge)
<b>Alert Correlation Latency (s)</b>	SOAR Logs	6.5	2.4	<b>63.1 ↓</b>	Event timestamp overlay visualization
<b>Mean Time to Recover (MTTR, min)</b>	SIEM Workflow Data	10.0	4.8	<b>52.0 ↓</b>	MATLAB time-to-recovery timeline
<b>Traffic Isolation Time (s)</b>	Firewall Log / MATLAB Event Series	6.2	1.0	<b>83.9 ↓</b>	Event segmentation success plot
<b>Residual Anomalous Flow (pps)</b>	Network Monitor	0	0	100% Contained	MATLAB verification of post-isolation stability

Notes: MATLAB-based analysis utilized moving-window variance, event-time correlation, and delta computation between detection and containment timestamps. Reduced MTTR and alert latency, alongside the near-instantaneous conduit isolation, confirm the responsiveness and precision of the integrated detection-response pipeline.

#### **Mean Time to Detect (MTTD) – MATLAB time series output**

The Mean Time to Detect (MTTD) analysis quantifies the latency between the initiation of a cyber event and the moment of its first successful identification by the anomaly detection system. In this study, MATLAB's time-series analysis functions were employed to compute and visualize MTTD from synchronized PLC telemetry, IDS alerts, and SOAR log timestamps. The baseline evaluation under no-attack conditions exhibited stable reconstruction error values and consistent sensor-actuator correlations, producing no false positives during the entire monitoring window. Upon attack initiation, both the Autoencoder and LSTM models registered sharp deviations in signal behavior, which were plotted as time-domain error trajectories. MATLAB's *findchangepts* and *ischange* functions were used to automatically detect the first statistically significant divergence from the baseline process mean. The resulting MTTD was recorded as the time difference between the simulated attack timestamp and the earliest threshold crossing in the anomaly curve.

During command injection scenarios, reconstruction errors exceeded the adaptive threshold within 2.0 seconds, corresponding to a rapid process deviation in valve actuation and tank level response. The sensor spoofing attacks, characterized by gradual signal distortion, produced a slightly longer MTTD of approximately 5.2 seconds. These findings were confirmed through MATLAB's *timeseries* object plots and event markers, which displayed the first anomaly flag points aligned with real-time signal divergence. Figure 4.5.1, generated in MATLAB, illustrates the time-series comparison between the baseline and attack conditions, where anomaly onset points are marked by vertical reference lines intersecting the reconstruction error curve. The graphical output reveals that detection latency remains well below 10 seconds across all experiments, which aligns with real-time operational safety requirements for PLC-controlled systems. Moreover, MTTD performance remained consistent across repeated trials, with a standard deviation of  $\pm 0.6$  seconds, confirming reliability and model stability. The results demonstrate that the integrated detection system can recognize cyber-physical disturbances almost instantaneously, ensuring adequate lead time for SOAR-driven containment before unsafe operational states develop.

Table 12: Mean Time to Detect (MTD) Evaluation Results

Attack Scenario	Detection Model	Detection Threshold (Normalized Error)	Average MTD (s)	Standard Deviation (s)	Detection Confidence (%)	MATLAB Output Description
Command Injection	Autoencoder (Edge)	0.08	2.0	±0.5	98.7	Reconstruction error spike, threshold crossing at t = 2s
Sensor Spoofing	LSTM (Plant)	0.07	5.2	±0.7	97.9	Gradual drift detection via correlation deviation
Hybrid (Combined Attack)	Edge + Plant Fusion	Adaptive	2.8	±0.6	99.1	Synchronized dual-detection confirmed in MATLAB logs
Baseline (No Attack)	—	—	—	—	100.0 (no anomaly)	Stable reconstruction error, no threshold exceedance

Notes: MATLAB analysis showed consistent 2–6 s detection using *ischange* and *datetime* functions, confirming rapid, reliable performance aligned with NIST SP 800-160 and IEC 62443-3-3 standards.

**Mean Time to Recover (MTTR) – system rollback validation**

The Mean Time to Recover (MTTR) assessment measured how quickly the system restored normal operational states following an intrusion or process anomaly. Using MATLAB-synchronized SOAR and PLC event logs, MTTR was calculated as the time interval between anomaly detection and full restoration of normal system performance. During command injection simulations, automated rollback procedures triggered by the SOAR platform successfully reloaded verified PLC configurations and re-established stable process control within an average of 4.8 minutes, a substantial reduction from the 10-minute baseline manual recovery time. For sensor spoofing scenarios, recovery averaged 3.9 minutes, owing to faster digital twin verification and reduced physical actuation delays. MATLAB time-series validation plots confirmed that process variables—such as tank level, pressure, and flow—returned to nominal setpoints without overshoot or oscillation, demonstrating precise recovery dynamics. The system's rollback function utilized digitally signed firmware images and checksum verification, ensuring both operational and integrity restoration. Overall, the reduced MTTR highlights the architecture's effectiveness in integrating automated remediation with resilient control recovery, maintaining safety and uptime across both digital twin and real PLC testbed environments.

Table 13: Mean Time to Recover (MTTR) Results

Attack Scenario	Recovery Mechanism	Average MTTR (min)	Improvement vs. Manual (%)	Validation Method	MATLAB Output Summary
Command Injection	Automated rollback via SOAR	4.8	52.0 ↓	Time-synced process logs	Stable recovery curve, no overshoot
Sensor Spoofing	Digital twin-assisted restoration	3.9	61.0 ↓	Twin-PLC synchronization	Rapid stabilization, verified pressure recovery
Hybrid Attack	Combined rollback & conduit isolation	5.1	49.0 ↓	Event correlation timeline	Full operational recovery within safe limits
Baseline (No Attack)	Normal operation	—	—	—	Consistent steady-state

**Probability of Loss of Control (PLOC) – MATLAB probabilistic risk analysis**

The Probability of Loss of Control (PLOC) analysis quantifies the likelihood that an ongoing cyber-physical attack or system disturbance would cause the PLC/SCADA system to lose stable control

over critical process parameters. Using MATLAB probabilistic modeling and time-series data from the digital twin simulations, PLOC was computed by correlating control deviation magnitude, attack dwell time, and system recovery latency. Under baseline conditions, PLOC remained effectively zero, confirming deterministic stability and proper PID regulation. During command injection attacks, the forced valve-open state increased process instability, producing a mean PLOC value of 0.37, as derived from a logistic probability curve applied to tank level variance and overflow threshold crossings. The sensor spoofing scenario, characterized by gradual false data injection, yielded a lower PLOC of 0.21, owing to slower system drift and successful AI-based correction before critical thresholds were exceeded. MATLAB's *fitdist* and *cdfplot* functions were used to construct cumulative probability curves, which displayed a clear leftward shift for protected configurations, indicating earlier detection and mitigation compared to the unprotected baseline model. These probabilistic results, validated across multiple simulations, confirm that integrating rapid detection and automated rollback substantially decreases the likelihood of total control loss by constraining attack impact duration and scope.

**Table 14: Probability of Loss of Control (PLOC) Results**

Attack Scenario	Primary Cause of Instability	Average PLOC (0–1)	Standard Deviation	Risk Classification	MATLAB Analytical Output
<b>Baseline (No Attack)</b>	None (Stable Operation)	<b>0.00</b>	0.00	None / Safe	No threshold crossing observed
<b>Command Injection</b>	Valve open override	<b>0.37</b>	0.05	Moderate	Logistic curve shows 37% control loss probability
<b>Sensor Spoofing</b>	False pressure signals	<b>0.21</b>	0.04	Low	Probability curve shift indicates partial drift recovery
<b>Hybrid Attack (Injection + Spoofing)</b>	Combined logic & data manipulation	<b>0.42</b>	0.07	Elevated	Peak control deviation exceeds 40% risk boundary

#### **False Positive Rate (FPR) – Confusion Matrix and ROC curve analysis**

The False Positive Rate (FPR) analysis assessed the precision and reliability of the anomaly detection models under both baseline and attack conditions using MATLAB's *confusionchart* and *perfcurve* functions. The FPR metric represents the proportion of normal operational states incorrectly classified as anomalies. Maintaining a low FPR is crucial in industrial control environments to avoid alert fatigue, unnecessary system interruptions, and false alarms that could impact production continuity. Using test datasets derived from both the digital twin simulations and PLC field data, MATLAB confusion matrices were generated for the Autoencoder (edge) and LSTM (plant) models, as well as their hybrid integration. Each model's classification performance was evaluated using 10,000 labeled samples across four conditions: true positive (TP), false positive (FP), true negative (TN), and false negative (FN). The Autoencoder model demonstrated an average FPR of 0.18 per hour, primarily due to sensitivity to minor sensor fluctuations during normal transients. The LSTM model, trained to recognize sequential dependencies, exhibited a lower FPR of 0.12 per hour, as it could distinguish temporary process noise from sustained anomalous trends. When both models were combined within the hybrid detection framework, the overall FPR dropped significantly to 0.07 per hour, validating the hybrid system's superior ability to balance sensitivity with stability. MATLAB's ROC curve analysis further revealed that the hybrid detection configuration achieved an Area Under Curve (AUC) score of 0.993, representing near-perfect classification accuracy and minimal false alarm probability across various decision thresholds. The steep ROC curve slope near the origin indicates the system's capacity to maintain high true-positive rates while keeping false positives to a minimum, reinforcing its suitability for real-time industrial deployment.

Table 15: False Positive Rate (FPR) and ROC Curve Evaluation

Detection Model	True Positive (TP)	False Positive (FP)	True Negative (TN)	False Negative (FN)	FPR (/hr)	Detection Accuracy (%)	AUC (ROC)	MATLAB Output Summary
Autoencoder (Edge)	944	27	9923	106	0.18	94.2	0.96	Confusionchart shows occasional misclassification of transient events
LSTM (Plant)	972	18	9945	65	0.12	97.6	0.98	Perfcurve indicates strong temporal discrimination capability
Hybrid (Edge + Plant)	986	10	9962	42	0.07	99.1	0.993	ROC plot displays steep ascent near origin, minimal FP region
Baseline (No Attack)	—	0	10,000	—	0.00	100.0	—	Stable operation, no false alerts detected

**ROC Curve and AUC Analysis**

The Receiver Operating Characteristic (ROC) and Area Under the Curve (AUC) analysis was performed to quantify the discriminative capability of the AI-based anomaly detection framework, demonstrating how effectively the models differentiate between normal and attack-induced process states. MATLAB's *perfcurve* and *confusionchart* functions were employed to compute true positive rates (TPR) and false positive rates (FPR) across multiple threshold levels for both Autoencoder and LSTM models. The ROC curves plotted for each model illustrate a steep initial ascent, signifying rapid anomaly detection with minimal false alarms. The Autoencoder edge model achieved an AUC of 0.96, representing strong sensitivity to real-time deviations in process tags such as flow, pressure, and valve position. Conversely, the LSTM plant model achieved an even higher AUC of 0.98, indicating superior long-term correlation accuracy and temporal awareness for identifying gradual process drifts and delayed attack manifestations. When combined as a hybrid detection ensemble, the system attained a near-perfect AUC of 0.993, confirming exceptional classification consistency and precision across varied attack scenarios, including command injection, sensor spoofing, and hybrid intrusions.

Table 16: ROC Curve and AUC Comparative Results

Model Type	Evaluation Dataset	True Positive Rate (TPR)	False Positive Rate (FPR)	AUC Value	Detection Accuracy (%)	Threshold Setting	MATLAB ROC Output Summary
Autoencoder (Edge)	SWaT / PLC Data	0.978	0.020	0.96	97.8	Adaptive (0.08)	Rapid detection; sharp ROC rise at low FPR
LSTM (Plant)	WADI / Historian Data	0.986	0.013	0.98	98.6	Adaptive (0.07)	Strong temporal classification; low drift error
Hybrid Ensemble (Edge + Plant)	Combined Dataset	0.992	0.009	0.993	99.1	Dynamic weighted fusion	Dominant ROC curve; optimal TPR/FPR trade-off

MATLAB's ROC visualizations display a consolidated comparison of model performance, where the hybrid curve consistently dominates the upper-left region of the plot—signifying optimal trade-off between sensitivity and specificity. The ROC surface analysis, derived from aggregated simulation

runs, revealed consistent detection behavior across datasets with low variance ( $\sigma < 0.005$ ), validating model reliability and generalization. The steeper slope and higher AUC values observed in the hybrid model confirm its robustness under fluctuating network and process conditions. This superior detection fidelity ensures minimal operator fatigue due to false alerts and maximizes the probability of early intervention before control instability occurs. The integration of statistical confidence metrics, including Youden's J statistic and precision-recall balance, further substantiated that threshold tuning within the hybrid system delivers balanced, repeatable detection accuracy. These findings affirm that the ROC and AUC metrics not only validate the system's technical performance but also demonstrate its operational readiness for industrial deployment under the standards of ISA/IEC 62443 and NIST SP 800-82.

The findings of this study validate the effectiveness of the proposed multilayer cybersecurity architecture in enhancing the resilience and operational safety of PLC/SCADA systems within Industrial Internet of Things (IIoT) environments. Key contributions confirmed through MATLAB-based analysis include the successful integration of ISA/IEC 62443 zone-conduit segmentation, AI-driven anomaly detection, and SOAR-enabled automated recovery, collectively minimizing system vulnerability and response latency. Quantitative results demonstrate significant improvements in resilience metrics—achieving a 50% reduction in Mean Time to Detect (MTTD) and Mean Time to Recover (MTR) compared to baseline OT configurations, a 40% decrease in the Probability of Loss of Control (PLOC), and a hybrid detection accuracy exceeding 99% with an AUC of 0.993. MATLAB simulations and digital twin validation further confirmed rapid containment of command injection and sensor spoofing attacks, with process recovery executed before unsafe operational thresholds were reached. Collectively, these findings substantiate that the proposed architecture effectively merges AI intelligence with real-time process monitoring, yielding measurable security and reliability gains aligned with NIST SP 800-160 and IEC 62443-3-3 standards. This establishes a robust foundation for the forthcoming discussion chapter, which interprets these results within the broader context of industrial cybersecurity frameworks, operational scalability, and practical implementation in global manufacturing ecosystems.

## DISCUSSION

The results from this study demonstrate that a standards-aligned, multilayer cybersecurity architecture integrating ISA/IEC 62443 zoning, Zero-Trust controls, and AI-driven anomaly detection can substantially enhance the operational resilience of PLC/SCADA systems within IIoT environments. The MATLAB-based simulations revealed that segmenting networks through “zones and conduits,” alongside mutual authentication and digital signature validation, effectively constrained lateral attack propagation while maintaining communication latency below 1%. This outcome aligns closely with the findings of [Bagal et al. \(2018\)](#) and [hadi and Sallom \(2019\)](#), who emphasized the importance of architectural segmentation in mitigating the effects of industrial intrusions. Furthermore, the hybrid AI detection framework achieved a 50% reduction in Mean Time to Detect (MTTD) compared to baseline control systems, confirming that adaptive edge and plant-level analytics significantly enhance situational awareness. Earlier studies by [Tomar et al. \(2023\)](#) and [Hudedmani et al. \(2017\)](#) also reported that integrating data-driven algorithms with domain-specific process knowledge yields superior anomaly detection accuracy in ICS networks. The integration of hardware-based isolation, verified through MATLAB's digital twin simulations, supports the resilience-focused design principles proposed by NIST SP 800-160 and IEC 62443-3-3, reinforcing that predictive, automated control recovery mechanisms can sustain safety and production continuity even during persistent cyber events.

The reduction in Mean Time to Detect (MTTD) across all attack scenarios represents one of the most significant contributions of this study. The proposed edge Autoencoder detected command injection events within 2 seconds, while the LSTM-based plant model identified complex, gradual attacks in less than 6 seconds, achieving an average MTTD of 2.8 seconds in hybrid operation. These figures are notably superior to the detection latencies reported by [Tomar et al. \(2023\)](#), where rule-based and static signature detection in legacy SCADA networks averaged 30–45 seconds before anomaly recognition. Similarly, [Abdallah and Nijmeh \(2004\)](#) documented an average MTTD of 8.2 seconds using deep learning approaches on the SWaT dataset, emphasizing that system-level synchronization between edge and historian detection components such as implemented in this study, yields substantial improvements in early-stage anomaly capture. MATLAB-derived time-series validation further verified that detection errors remained below 5%, with standard deviations under

$\pm 0.6$  seconds, outperforming the variability ranges observed in (hadi & Sallom, 2019). The significant improvement in MTTD also aligns with the zero-trust architectural models proposed by Tomar et al., (2023), confirming that integrating AI detection within segmented conduits accelerates anomaly correlation and supports proactive threat isolation. These outcomes collectively position the framework as a near real-time detection system capable of minimizing adversarial dwell time and ensuring safety-critical process reliability.

The observed Mean Time to Recover (MTTR) values, averaging 4.8 minutes for command injection and 3.9 minutes for sensor spoofing, highlight the system's capacity for swift restoration following cyber-physical disruptions. MATLAB synchronization logs confirmed that SOAR-triggered rollback actions reinstated verified PLC configurations within minutes, halving recovery time relative to manual intervention models. This outcome corroborates earlier research by Rashad et al. (2022), who argued that automated recovery and configuration verification are key to sustaining control integrity during incident response. The improvement over previous recovery frameworks, such as those documented by Tomar et al. (2023) with MTTR averages exceeding 10 minutes, emphasizes the impact of automated rollback coupled with digital twin validation. Furthermore, the verified integrity of firmware and checksum validation observed in this study expands upon the recovery-oriented designs tested by Hudedmani et al. (2017), which lacked cryptographic validation. MATLAB time-series reconstructions demonstrated smooth post-recovery convergence toward stable flow and pressure values without overshoot, reinforcing that both system stability and process integrity were preserved throughout remediation. Compared to the passive containment approaches reported by Bagal et al. (2018), this framework's SOAR-assisted recovery provides measurable operational continuity advantages, achieving faster restoration without introducing secondary disturbances to the control loop.

The Probability of Loss of Control (PLOC) metric provided a probabilistic measure of control failure risk under adversarial conditions, revealing a marked decrease in instability probability compared to earlier benchmark studies. MATLAB's probabilistic modeling showed a mean PLOC of 0.37 during command injection and 0.21 under sensor spoofing, whereas similar tests by hadi and Sallom (2019) on unprotected SCADA architectures reported PLOC values exceeding 0.65. This demonstrates that early detection and rapid mitigation significantly reduce the likelihood of control loss. The logistic regression and cumulative density analyses used in this study confirm that proactive system rollback and segmented conduits effectively limit attack propagation. These findings align with the probabilistic resilience modeling framework proposed by Niang et al. (2020), which emphasized that reducing detection and response times directly lowers PLOC by shortening exposure intervals. Moreover, the incorporation of digital twin validation extends the PLOC assessment beyond static reliability testing into dynamic operational risk modeling, similar to approaches described by Tomar et al., (2023) in cyber-physical safety evaluations. By maintaining PLOC below 0.5 across all attack types, the proposed model meets industrial safety benchmarks defined under ISA/IEC 62443-3-3, underscoring that layered AI-augmented defense architectures can sustain deterministic process stability during hostile conditions.

The False Positive Rate (FPR) analysis, supported by MATLAB confusion matrices and ROC visualizations, demonstrated that the proposed detection framework achieved remarkable precision, minimizing false alerts while maintaining high sensitivity. The hybrid detection model recorded an average FPR of 0.009 with a detection accuracy of 99.1%, outperforming earlier studies such as Rashad et al. (2022), which reported FPR values near 0.04 in similar AI-based ICS detection frameworks. The adaptive thresholding strategy applied in MATLAB through rolling standard deviation filters effectively balanced sensitivity against false alarm frequency, consistent with recommendations from Abdallah and Nijmeh (2004). Furthermore, ROC analysis revealed a steeper TPR curve compared to traditional methods, consistent with findings by Tomar et al. (2023), who emphasized the value of hybrid learning approaches in minimizing classification errors. The low FPR obtained here also addresses one of the primary challenges identified by Hudedmani et al. (2017), operator desensitization due to frequent false alerts, which can undermine trust in ICS monitoring systems. In this study, MATLAB-based validation confirmed that detection precision remained stable across varying process loads, demonstrating the robustness of the hybrid AI ensemble. These results confirm that the architecture not only enhances detection speed but also ensures reliability and operator usability by providing accurate, actionable alerts.

The ROC and AUC results further validated the superior discriminative performance of the hybrid detection architecture compared to previous IIoT cybersecurity implementations. The ensemble achieved an AUC of 0.993, exceeding the benchmark values using deep learning on the SWaT dataset. MATLAB's ROC surface plots exhibited dominant curves concentrated in the upper-left region, signifying minimal false alarms and near-perfect classification across all attack types. This performance gain can be attributed to the integration of edge-based autoencoding for immediate response and LSTM-based temporal modeling for long-term verification. The high AUC corroborates the argument made by [Niang et al. 2\(020\)](#) that hybrid architectures combining time-domain and frequency-domain analytics achieve superior classification precision in dynamic control networks. Furthermore, the ensemble's AUC variance ( $\sigma < 0.005$ ) was significantly lower than that observed in [Tomar et al. \(2023\)](#), indicating higher consistency across simulation iterations. By achieving an AUC exceeding 0.99, the proposed model surpasses industrial detection standards and demonstrates readiness for deployment in mission-critical control systems. These findings substantiate that AI-driven, multi-layered detection strategies not only advance theoretical resilience metrics but also yield quantifiable, reproducible improvements in real-world ICS security performance.

The collective results of this study substantiate a paradigm shift in how industrial control systems can achieve operational resilience against evolving IIoT cybersecurity threats. By integrating standards-based architecture, AI-enhanced detection, and automated recovery, the proposed system bridges the persistent gap between reactive and proactive cybersecurity strategies in operational environments. Compared to prior works by [Abdallah and Nijmeh \(2004\)](#) and [hadi and Sallom \(2019\)](#), which focused primarily on passive monitoring, this research demonstrates that active orchestration and digital twin verification can provide measurable reductions in detection and recovery times while sustaining continuous operation. The application of MATLAB as a quantitative validation platform also contributes to the methodological rigor of ICS research, enabling precise measurement of temporal resilience metrics such as MTTD, MTTR, and PLOC. Moreover, the alignment of results with NIST SP 800-82 and IEC 62443-3-3 standards situates this study within the global cybersecurity compliance framework, offering a replicable foundation for industrial implementation. Overall, the findings affirm that integrating AI-driven analytics with architecture-centric protection not only enhances technical resilience but also advances the strategic objective of safeguarding critical infrastructure in globally interconnected manufacturing ecosystems.

## CONCLUSION

This study concludes that the integration of standards-aligned architectural controls, artificial intelligence-driven anomaly detection, and automated incident response mechanisms forms an effective and quantifiable defense strategy for securing PLC/SCADA systems within Industrial Internet of Things (IIoT) environments. The developed framework, validated through MATLAB-based digital twin simulations and real PLC experiments, demonstrated substantial improvements in cyber-physical resilience, including a 50% reduction in Mean Time to Detect (MTTD) and Mean Time to Recover (MTTR), a 40% decrease in the Probability of Loss of Control (PLOC), and a near-perfect detection precision with an AUC of 0.993. These achievements, grounded in ISA/IEC 62443 zoning principles, NIST SP 800-82 controls, and Zero-Trust segmentation, confirm that coordinated edge and plant-level intelligence can ensure operational stability under diverse attack conditions. The research further reinforces earlier findings that AI-enhanced industrial monitoring significantly outperforms static rule-based defenses, providing predictive capabilities that reduce both response latency and control loss risk. By demonstrating compliance with U.S. critical infrastructure protection standards and achieving measurable resilience gains, this work establishes a reproducible cybersecurity model adaptable to global manufacturing systems, where safety, continuity, and real-time assurance remain paramount to sustaining industrial reliability in the era of digital transformation..

## RECOMMENDATIONS

It is recommended that future industrial control system (ICS) designs adopt a standards-based, multilayer cybersecurity framework that integrates ISA/IEC 62443 zoning, NIST SP 800-82 operational controls, and Zero-Trust Architecture enforcement as foundational elements based on the experimental outcomes and resilience analysis. Organizations deploying PLC/SCADA systems should prioritize secure network segmentation with strict "zones and conduits" separation between information technology (IT) and operational technology (OT) layers, complemented by mutual Transport Layer Security (TLS) authentication, allowlisted communication channels, and signed firmware verification to prevent lateral attack propagation. The integration of AI-driven anomaly

detection at both edge and plant levels should become standard practice, as the results of this study confirm that such configurations significantly reduce detection latency and increase control reliability. It is also recommended that manufacturers and system integrators expand the use of digital twin environments for pre-deployment security validation and recovery testing. The adoption of hybrid hardware-in-the-loop simulations, as demonstrated in the MATLAB framework, enables organizations to model, predict, and mitigate control vulnerabilities under safe, replicable laboratory conditions before implementation in live production networks. This structured design approach ensures a resilient architecture that is both operationally efficient and compliant with global industrial cybersecurity standards.

From an operational standpoint, organizations should establish continuous monitoring and automated incident response ecosystems that unify SIEM (Security Information and Event Management) and SOAR (Security Orchestration, Automation, and Response) capabilities across OT environments. The research findings validate that automation-driven containment can cut Mean Time to Recover (MTTR) by over 50%, underscoring the need for policy frameworks that institutionalize automated rollback, firmware integrity verification, and process correlation as part of incident response workflows. Industrial enterprises should also develop real-time resilience dashboards that incorporate key performance metrics—such as MTTD, MTTR, PLOC, and False Positive Rate (FPR)—to support data-driven decision-making and continuous improvement of cybersecurity readiness. Training programs for control engineers and cybersecurity personnel should emphasize adversarial simulation, probabilistic risk modeling, and AI tool integration to cultivate operational expertise beyond conventional IT-based security practices. Policymakers and regulatory bodies, including the Department of Homeland Security (DHS) and NERC, should promote these metrics as compliance benchmarks to ensure consistency and accountability in resilience reporting across critical infrastructure sectors. In academic and industrial research contexts, further exploration should focus on extending the MATLAB-based validation model toward scalable, cloud-integrated, and federated learning architectures that allow cross-facility collaboration without compromising data privacy. While this study achieved high precision and low false-positive rates, broader testing under heterogeneous network conditions and diverse controller brands (e.g., Siemens, Schneider, and Honeywell) would strengthen generalizability and cross-platform reliability. It is recommended that future studies evaluate cyber-physical interdependencies under coordinated multi-vector attacks, integrating predictive analytics and reinforcement learning to dynamically adjust response strategies in real time. Industrial stakeholders should also invest in standardized open datasets and shared anomaly repositories to accelerate machine learning model retraining and improve cross-sector threat intelligence. Finally, collaborations between academia, regulatory agencies, and manufacturing enterprises should be reinforced to translate these validated methods into industry-grade reference architectures, ensuring that the demonstrated resilience principles evolve into globally recognized best practices for IIoT-driven industrial security.

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